ISR Lab Video Transcript :00 [Music] 0:00 foreign 0:05 lab the intelligence and system robotics 0:08 lab here at UWF Pensacola Florida in 0:12 here this is where we essentially this 0:14 is where the robotic magic happens in 0:16 the rsr lab it's mostly connected as 0:17 well to ihmc with the resource team and 0:19 development we just basically take those 0:22 three parts of the engineering and we 0:23 apply them to real life situations or on 0:25 research for things like aerial drones 0:28 or anything biomechanical that can be 0:29 applied to a real life I've learned a 0:32 lot about autonomous robots and and just 0:35 learning how robots move how we're able 0:37 to use science and math and physics and 0:41 things like that to like simulate and 0:43 emulate 0:44 real life motion and things like that 0:47 here what I'm working on in the ISR lab 0:49 is I'm working on a simulation that is 0:53 dealing with a quad rotor a UAV the 0:56 acronym stands for the unmanned aerial 0:58 vehicle and from there I am supposed to 1:01

simulate the AV to Target a specific 1:05

object so right now I'm working on a

project with a robot called The Jet hexa 1:10

and I'm using the robot to detect tennis 1:13

balls so it's he's a ball if it's a

1:15

circular shape it's yellow it says the 1:17

tennis ball and then you have to run 1:19

algorithms and stuff to make sure it 1:21

actually is a tennis ball and then the 1:23

robot will move to align itself with it

so right now I'm working on a quadruped 1:29

robot it essentially it has a lidar 1:31

sensor and then a webcam in front of it 1:33

it essentially Maps out an entire room 1:35

and then I can either plan a single path 1:37

or a couple of waypoints and the robot 1:40

will generate a simulation to where it 1:42

finds the quickest and most efficient 1:43

route to get there without running into 1:45

any obstacles it can be it can be 1:48

intimidating at first so for me I had no 1:51

experience with robotics coming in it 1:53

definitely makes you think differently 1:55

because you're applying all these 1:56

courses into One Singular action so you 1:59

have all the math you have all the data 2:01

analytics you have the mechanical and 2:03

electrical aspects of it and then you

have to think and then make your thought 2:08

process go into fixing this problem

2:10

solving it rather than just putting all 2:12

these pieces together and hoping that 2:13

the outcome comes out perfectly and you 2:16

just have to take time and you have to 2:17

have patience and you have to do a bunch 2:20

of trial and error and no matter how

many errors you get you just have to 2:24

keep going and there's a lot of useful 2:27

resources and helpful staff and students 2:30

who are willing to help you we have each 2:32

other to ask questions because all of us 2:34

are going through the same thing or have 2:35

been struggling with the same problems 2:37

so having each other is definitely the 2:39

number one like resource for each other 2:42

so when I think about who I was as a 2:44

freshman I was someone who didn't really 2:46

like branching out or reaching out for 2:49

opportunities but I found as I got older 2:52

that the best opportunities for me the 2:55

ones where I grew the most were the 2:57

opportunities that I sought after myself 2:59

so reaching out to faculty members

3:02

talking to different people to different

3.05

classmates those were the the times when

3:09

I had to really stretch and grow and

3:12

develop skills that

3:14

made me a better student a better person

3.17

a better roboticist all the above so I

3:20

would definitely recommend reaching out

3:22

and trying to find your own

3:24

opportunities